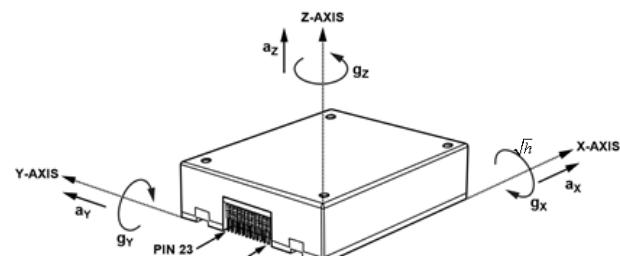
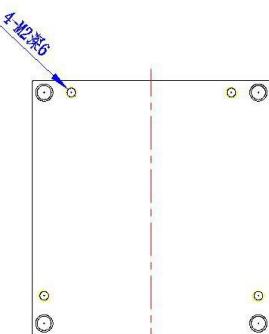
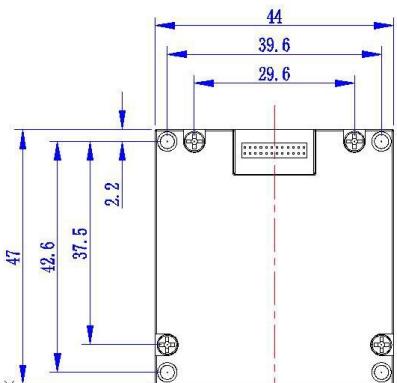


16488-C MEMS IMU



16488-C is a domestic MEMS IMU used to replace ADIS16488. The product precision is better than ADIS16488. The version is optional, the size and appearance are exactly the same, and the communication protocol is the same. The version is optional, the size and appearance are exactly the same, and the communication protocol is the same. It is more convenient for users to change, providing users with professional product customization services.



| | Parameter | Conditions | 16488-C | ADIS16488 | unit |
|----------------------------|--------------------------------------|------------------------------|----------------------------|----------------------|---------------------|
| Gyro | Dynamic measuring range | configurable | ± 450 | ± 480 | $^{\circ}/s$ |
| | Bias instability | Allan | 3.5 | 5.1 | $^{\circ}/h$ |
| | bias stability | 1s, rms | 30 | / | $^{\circ}/h$ |
| | bias in full temperature range | -40°C~85°C, 10s, rms | 0.02 | / | $^{\circ}/s$ |
| | Random walk | 16 | 0.25 | 0.26 | $^{\circ}/\sqrt{h}$ |
| | bias repeatability | 16 | 35 | / | $^{\circ}/h$ |
| | output noise | No filtering, rms | 0.09 | 0.135 | $^{\circ}/s$ |
| | Scale factor repeatability | 16 | 0.02 | 1.0 | % |
| | Scale factor Temperature coefficient | -40°C~85°C, 16 | 5 | ± 35 | ppm/°C |
| | The scale factor is nonlinear | FS=450°/s | 0.008 | 0.01 | %FS |
| Accelerometer | bandwidth (-3dB) | | 330 | 330 | Hz |
| | Dynamic measuring range | Configurable (Max ± 40) | ± 20 | ± 18 | g |
| | bias stability | Allan error | 0.005 | / | mg |
| | bias in full temperature range | -40°C~85°C, 10s, rms | 0.5 | 16 | mg |
| | Random walk | 16 | 0.01 | 0.029 | m/s/Vh |
| | Bias instability | 16 | 0.16 | / | mg |
| | output noise | No filterin, rms | 1 | / | mg |
| | Scale factor repeatability | 16 | 0.01 | 0.5 | % |
| | scale factor is nonlinear | FS=10g | 0.002 | 0.1 | %FS |
| Magnetometer | bandwidth (-3dB) | | 330 | 330 | Hz |
| | Cross coupling | | 0.18 | / | % |
| | Dynamic measuring range | | ± 2.5 | ± 2.5 | gauss |
| | The sensitivity | | 0.1 | 0.1 | mgauss/LSB |
| Barometer | nonlinearity | | 0.5 | 0.5 | %FS |
| | Pressure range | | 1100 | 1100 | mbar |
| | sensitivity | | 6.1×10^{-7} | 6.1×10^{-7} | mbar/LSB |
| | Total error | | 4.5 | 4.5 | mbar |
| | The relative error | | 2.5 | 2.5 | mbar |
| Communication interface | nonlinearity | | 0.1 | 0.1 | %FS |
| | 1 way SPI | Input clock frequency | 15 | 15 | MHz |
| | 1 way UART | Baudrate | 230.4 | / | kbps |
| Electrical characteristics | 1 way CAN | | / | / | kbps |
| | voltage | dc | 3.3 (or 5) $\pm 10\%$ | V | |
| | Power consumption | | 0.6 | 1 | W |
| Environment | ripple wave | P-P | | 100 | mV |
| | working temp. | extensible | | 85 | °C |
| | Store temp | | | 85 | °C |
| | vibration | | 10~2000Hz, 6.06g | | |
| | impact | | 5000g, 0.1ms | | |